

MERI College of Engineering & Technology (MERI-CET)

Session: 2020-2021
Department: CSE

Subject code: CSE-407-F

Course- CSE Semester: 7th

Faculty Name: Ms. PREETI

Lesson plan

Name if the faculty : Ms.PREETI

Discipline : Computer Science Engineering

Semester : 7th

Subject : Neural Networks

Lesson Plan Duration: 14 weeks (From August, 2020 to November 2020)

Work Load (Lecture/ Practical) per week (in hours): Lecture-03, Practical-02

| Week | Theory | | Practical | |
|-----------------|--------------------|---|-----------------|---|
| | Lecture day | Topic(Including assignment/test) | Practical Day | Topic |
| 1 st | st 1 nd 2 | Overview of biological neurons Structure of biological neurons relevant to ANNs Structure of biological neurons relevant to ANNs, Fundamental concepts of Artificial Neural Networks, | 1 st | How the weights and bias values affect the output of a neuron. |
| 2 nd | st 1 nd 2 | Models of ANNs Models of ANNs, Feedforward & feedback networks learning rules | 2 nd | How the weights and bias values affect the output of a neuron. |
| 3 rd | st 1 nd 2 3 rd | Hebbian learning rule perception learning rule Delta learning rule, Widrow-Hoff learning rule | 3 rd | How the choice of activation function (or transfer function) affects the output of a neuron |
| 4 th | st 1 nd 2 | correction learning rule Winner –lake all elarning rule, etc, Winner –lake all elarning rule, etc | 4 th | Experiment with the following functions: identity (purelin) |



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| | 3 rd | Revision of 1st unit with test | | |
|-----------------|-----------------|--|-----------------|--|
| 5 th | st 1 | Single layer Perception Classifier | | Experiment with the following functions: |
| | 2 | Classification model, Features & Decision regions | | binary threshold (hardlim, hardlims) |
| | 3 rd | training & classification using discrete perceptron | | |
| 6 th | st 1 | algorithm | 6 th | Experiment with the following functions: |
| | nd 2 | single layer continuous perceptron networks for linearly seperable classifications | | |



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| | 3 rd | single layer continuous perceptron networks for linearly seperable classifications | | sigmoid (logsig, tansig). |
| 7 th | 1 st | Revision of 2 nd unit with test | 7 th | How the weights and bias values are able to represent a decision boundary in the feature space |
| | 2 nd | Multi-layer Feed forward Networks | | |
| | 3 rd | linearly non-seperable pattern classification, Delta learning rule for multi-perceptron layer | | |
| 8 th | 1 st | generalized delta learning rule | 8 th | How this decision boundary changes during training with the perceptron learning rule |
| | 2 nd | Error back propagation training | | |
| | 3 rd | learning factors, Examples | | |
| 9 th | 1 st | Single layer feed back Networks | 9 th | How the perceptron learning rule works for linearly separable problems |
| | 2 nd | Basic Concepts | | |
| | 3 rd | Hopfield networks, Training & Examples | | |
| 10 th | 1 st | Revision of 3 rd unit with test | 10 th | How the perceptron learning rule works for linearly separable problems |
| 10 | 2 nd | Associative memories | | |
| | 3 rd | Linear Association, Basic Concepts of recurrent Auto associative memory | | |
| 11 th | 1 st | retrieval algorithm | 11 th | How the perceptron learning rule works for non-linearly separable problems |
| | 2 nd | storage algorithm | | |
| | 3 rd | by directional associative memory | | |
| 12 th | 1 st | Architecture | 12 th | How the perceptron learning rule works for non-linearly separable problems |
| | 2 nd | Association encoding & decoding | | |
| | 3 rd | Stability, Self organizing networks | | |
| 13 th | 1 st | UN supervised learning of clusters | 13 th | Revision of Practicals |
| | 2 nd | winner-take-all learning | | |
| | 3 rd | Recall mode, Initialization of weights Initialization of weights Initialization of weights Initialization of weights Initialization of weights. | | |
| 14 th | 1 st | seperability limitations | 14 th | Revision of Practicals |
| | 2 nd | Revision of 4 th unit with test | | |